

APPENDIX 1

```

void sw ( )
(
5      #define iw = 12;                                /* instruction
                                                    width */
                                                    /* memory width */
      #define mw = 3:
      #define CONST = 0
10     #define LOAD = 1
      #define GLOBAL = 2
      #define PUTCHAR, = 15 /*
                                                    put a character along the
                                                    standard output channel*/
      #define GETCHAR = 16 /*
15     get a character from the
                                                    standard input channel */

      ...

      rom program []
20     #include "prog.o" ): ram stack[1<mw] with dualport = 1 ];
      ram memory[1<mw] unsigned iw PC, ir, tos;
      unsigned mw sp;

      do par it = program[pc]: PC = PC + 1;
25     tos = stack[sp-1];
                                                    /* save top of
                                                    stack to avoid
                                                    two ram accesses
                                                    in one cycle
                                                    */

30
      switch (ir)
      case
      CONST par
          stack[sp] = program[pc];
35          sP = sP+1;
          PC = Pc+1;
          ]
          break;
      case LOAD
40          stack[sp-1] = memory[tos<-mw];
          break;
      case STOP break; default :
                                                    /* unknown opcode */
      while (1) delay;

45 ] while (ir != STOP);

```

]

Register transfer level description of simple processor

5

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APPENDIX 2

```
void main() { char hwswwchan;
char unsigned 8 port:
```

5

```
par {
    parallel_,port(port);
    SyncGen():
```

10

```
initialiseRam(port);
par {
    display(hwswhchan): sw(hwswhchan);
y 1 }
```

}

15

RTL description of main

APPENDIX 3

CALCULATION PROCESS

```

5  /*
   * Channel communicating object positions
   */ chap unsigned 17 position;

   /*
10  * Channel communicating segment information
   */
   chanout unsigned 9 segment;

   /*
15  * Channel communicating button information
   */
   chanin unsigned 2 buttons;

   /*
20  * Overall par
   */ par

       /*
25  * Mass motion
   */

       /*
       * Positions of each mass, 9+8 fixed point
       */
30  unsigned 17 p0, p1, p2, p3, p4, p5, p6, p7;
       /*
       * Velocity of each mass, 9+8 fixed point
       */
       int 17 v1, v2, v3, v4, v5, v6, v7; '
35  /*
       * Accelerations of each mass, 9+8 fixed point
       */
       int 17 a1, a2, a3, a4, a5, a6, a7;
       /*
40  * Sutton status
   */
   unsigned 2 button status;
   /*
45  * Initial setup of positions
   */

```

```

p0 = 65536;
p1 = 65536;
p2 = 65536;
p3 = 65536;
5  p4 = 65536;
p5 = 65536;
p6 = 65536
p7 = 65536

10
    /*
    * Forever
    */
    while (1)
15    {

        /*
        * Send successive positions down position channel
        */
20    send(position, p0);
    send(position, p1);
    send(position, p1);
    send(position, p2);
    send(position, p2);
25    send(position, p3);
    send (position, p3);
    send(position, p4);
    send(position, p4);
    send(position, p5);
30    send(position, p5);
    send(position, p6);
    send(position, p6);
    send(position, p7);

35    /*
    * Update positions according to velocities
    */
    p1 +_ (unsigned 17)v1;
    p2 +_ (unsigned 17)v2;
40    p3 +_ (unsigned 17)v3;
    p4 +_ (unsigned 17)v4;
    p5 +_ (unsigned 17)v5;
    p6 +_ (unsigned 17)v6;
    p7 +_ (unsigned 17)v7;

45    /*

```


DISPLAY PROCESS

```

5  /* standard includes */
    #include "hammond.h"
    #include "syncgen.h"
    #include "stdlib.h"
10  #include "parallel.h"

    /*
    * Segment information channel */ chap segment;

15  /*
    * Button information channel */
    chan buttons:

        /
20  * Include dash generated stuff */
    #include "handelc.h"

    /*
    * Main program */
25  void main() (
        /
    * Scan positions
    */ unsigned sx, sy;

30  /
    * Vdeo output register
    */
    unsigned 1 video;

35  /*
    * Video output bus
    */

    interface bus out() video out(Visible(sx, sy) ?
40  (video ? (unsigned 12)0xffff : 0) 0) with video spec;

    #ifndef SIMULATE
        /*
        * Left button input bus
45  */
    interface bus in (unsigned 1) button_left()

```



```

with button white spec;

/*
 * Right button input bus
5 */
    interface bus in(unsigned 1) button right()
        with button_black spec;
    #endif

10 /*
 *
    Overall par
    */ par {
/*
15     * VGA sync generator
    */
    SyncGen(sx, sy, hsync pin, vsync pin);
/*
    *
20     Dash generated hardware
    */
    hardware();
/*
    * Run-length decoder
25     */
    {
/*
    * Segment start and end positions
    * /
30    unsigned start, end;
/*
    * Forever
    */
    while (1)
35    {
        while (sy != 448)
            /*
            * Read segment information
            */
            segment ? start;
40            segment ? end;
            /*
            * Get in the right order
            */
            if (start > end)
45            {

```

```

                                par
                                {

5      end = start;
      start = end;
    )

                                /*
10     * Make at least 1 pixel visible
      */
      if (start == end)
                                end++;

15     /*
                                * Wait
      */
                                while (sx != 0)
                                  delay;
20     /*
      * Draw a scanline worth
      */
      while (sx != 512)
        if ((sx <- 9) >= start && (sx <- 9) < end)

25          video = 1;
          else
            video = 0;

30          )
      /*
      * Communicate button status
      */
      #ifdef SIMULATE
35          buttons ! 1;
      #else
          buttons ! button left.in @ button right.in;
      #endif

40     /*
      * Wait
      */
      while (sy != 0)
        delay;

45     )

```